Sorting Multisets in Anonymous Rings*

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Abstract

An anonymous ring network is a ring where all processors (vertices) are totally indistinguishable except for their input value. Initially, to each vertex of the ring is associated a value from a totally ordered set; thus, forming a multiset.

In this paper we consider the problem of sorting such a distributed multiset and we investigate its relationship with the election problem.

We focus on the computability and the complexity of these problems, as well as on their interrelationship, providing strong characterizations, showing lower bounds, and establishing efficient upper bounds.

1. Introduction

An *anonymous* ring network $R = r_1, \ldots r_n$ is a ring where all processors (or vertices) are totally indistinguishable except for their input value. Notice that indices are used only for clarity of discussion and are not known to the vertices. From a computational viewpoint, anonymous systems are the least powerful distributed systems, and hence the ideal setting to study the complexity of problems and the relationship among them.

Initially, to each vertex r_i of the ring is associated a value s_i from a totally ordered set $\mathcal{V}$. The associated values form a *multiset* $S = \{s_1, \ldots, s_n\}$, where $s_i \in \mathcal{V}$. Let us denote by $\delta(S)$ the number of distinct elements of $\mathcal{V}$ which appear in S.

The particular case when $\delta(S) = n$ corresponds to the case when S is actually a set; i.e., each vertex has a distinct input value. In this case, the network is not really anonymous since the distinct values can be used as identities and allow to distinguish among the vertices. Networks with distinct values have been extensively studied in the literature and problems such as: leader election, edge election, minimum and maximum finding, sorting, topology recognition have been solved and analyzed in several asynchronous network topologies (e.g., [11]).

In the case of a general multiset (i.e. $\delta(S) < n$), unfortunately very little is known. Most of the existing results focus on the Boolean case (i.e., $\delta(S) \leq 2$) and study the problem of computing Boolean functions (such as OR, AND, XOR) [2, 3, 4, 5, 8, 12]. For the general case, only a few distributed problems have been studied: finding the extrema of the multiset [1], and finding the multiplicity of a value in the multiset [1].

In this paper we consider the problem of *sorting* the multiset (*MSP*) in asynchronous anonymous rings, and we investigate its relationship with the vertex and edge election problems (*VE*, *EE* respectively) and with the general election problem GEP.

Sorting the multiset means that, at the end of the computation, the values must be placed on the ring so to be ordered in a direction starting from a vertex; the choice of the vertex is not predetermined. The sorting problem has been extensively studied when the values are distinct (or the network is not anonymous) (e.g., see [10, 13]); however, it has never been investigated in the case of multisets.

The vertex election problem *VE* consists in starting from a situation where the network is anonymous and ending in a situation where a vertex is different from the others. Analogously, in the edge election problem *EE*, an edge must become different from all others, and identified as the leader. The general election problem *GEP* is the problem of electing, if possible a vertex, otherwise an edge.

Clearly the solvabilty of these problems depends on many factors including the input values, the value of n (the ring size), the fact that the ring is oriented or not, etc. Since any non-trivial problem is unsolvable if n is unknown to

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the vertices [3], we will assume in the following that n is a priori known.

In this paper we focus on the computability and the complexity of these problems, as well as on their interrelationship, providing strong characterizations, proving lower bounds, and establishing efficient upper bounds. For example, it is well known that, if S is not a set, the election problems are in general not solvable; but no characterization existed. We provide one by showing that, for a general multiset, GEP is solvable if and only if S is aperiodic.

On the relationship among the sorting and the election problems we provide a complete characterization. Interestingly, we prove that the solvability relationship among these problems depends on the value of $\delta(S)$. As we show, the characterization is rather simple for the cases $\delta(S) \neq 2$; the situation when $\delta(S) = 2$ is more complex, and it depends on several factors including the ring orientation and the value of n.

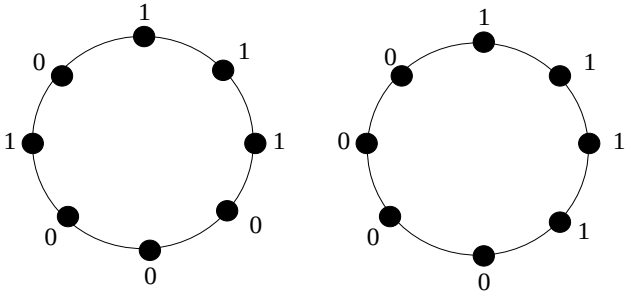
We then focus on the complexity of solving these problems and study the Boolean setting (i.e., $\delta(S) \leq 2$). We first present an algorithm for oriented rings of prime size; this algorithm solves the sorting and election problems using at most $O(\sum_{j=1}^{l}({z_j}^2 + {t_j}^2) + n \log n)$ messages, where z_j and t_j are the lengths of the consecutive blocks of 0's and 1's in S, respectively. We also present an algorithm for oriented rings of not-prime size; this algorithm solves the election and sorting problems (if a solution exists) using on average $O(n \log n)$ messages. The same bounds are shown to be achievable also for *unoriented* rings. Finally we present some lower bounds; these bounds prove that the algorithms for the case of n prime are optimal. We also show that, when n is not prime, any solution to these problems requires the exchange of $\Omega(n \log n)$ messages for almost all multisets S; hence, for almost all inputs, the algorithms for the case of n not prime are average-case optimal.
For sake of brevity, almost all the proofs have been omitted and can be found in [6].

2. Definitions

Let $R = r_1 \dots r_n$ be an anonymous ring of n processors. We say that R is *oriented* if all processors agree on the same direction (e.g., clockwise), otherwise R is *unoriented*.

To each vertex r_i of the ring it is associated a value s_i from a totally ordered set $Z_v = \{0, \dots, v-1\}$; the associated values form a *multiset* $S = \{s_1, \dots, s_n\}$, where $s_i \in Z_v$.

In the following we will consider such a multiset as a string of values. More precisely, the multiset corresponds to a v-*valued* string $S = s_1 \dots s_n$ of length n where $s_i \in Z_v = \{0, \dots, v-1\}$, $1 \leq i \leq n$. We denote by $d_u(S)$ the multiplicity of $u \in Z_v$ in S, by $\delta(S)$ the number of distinct values u with $d_u(S) > 0$, and by $R(S)$ the ring R with input S , i.e., s_i being the input of node r_i.



a) Unsorted string b) Sorted string

Figure 1. A a) unsorted and b) sorted ring.

Given $k \in \{1, \dots, n\}$ we denote by $\sigma^k(S)$ the k-th *cyclic shift* (or simply *shift*) of S, i.e., $\sigma^k(S) = s_k s_{k+1} \dots s_{k-1}$ where all indices are modulo n. We denote by $\sigma(S)$ the *multiset* $\{\sigma^k(S) | 1 \leq k \leq n\}$ and by $\mu(\sigma^k(S))$ the *multiplicity* of $\sigma^k(S)$ in $\sigma(S)$; if $\exists i$ such that $\mu(\sigma^i(S)) = 1$ then we say that S is *unique*. We also say that the string is *periodic* with *period* k if $S = s_1 \dots s_n = (s_1 \dots s_k)^{\frac{n}{k}}$ and $1 \leq k < n$, otherwise the string is *aperiodic*. Finally we denote by $\bar{S}$ the reverse string of S, i.e., $\bar{S} = s_n \dots s_1$.

A v-valued string S is *canonic* if $s_1 \neq s_n$. Obviously, every S with $\delta(S) > 1$ has a shift that is a canonic string; therefore, w.l.o.g., we only consider canonic strings, where $\delta(S) > 1$.

Property 1 *A string S is unique iff it is aperiodic. Furthermore, S is unique iff $\bar{S}$ is unique.*

Property 2 *In every aperiodic string S the lexicographical minimal shift is unique.*

Property 3 *If n is prime then every string S, is aperiodic.*

A v-valued string $S = s_1 \dots s_n$ is *sorted* iff $\exists\, \sigma^i(S), 1 \leq i \leq n$, such that $\sigma^i(S) = 0^{d_0(S)} 1^{d_1(S)} \dots u^{d_u(S)} \dots (v-1)^{d_{v-1}(S)}$, where u^0 is the empty string. Note that for $\delta(S) \leq 2$, if S is sorted, so is $\bar{S}$.

We consider several inter-related problems. The main focus of this paper is on the sorting problem.

Problem 1 Multiset sorting problem (MSP)
Given an (un)oriented ring R and a v-valued string S, move from $R(S)$ to a final configuration $R(S')$ where:

1. $\forall u \in Z_v, \delta_u(S) = \delta_u(S')$;
2. *$R(S')$ is sorted.*

An example for $v = 2$ is shown in Figure 1.

We will study MSP in relation to the classical problems of vertex election (VE) and edge election (EE). Vertex election is the most basic problem in distributed computing (see [11]); the edge election problem has been widely studied in detail in [15]; when an edge is elected, both vertices know about it (e.g., are in a special state).

In addition, we will focus on the more general formulation of the problem which integrates both VE and EE.

Problem 2 General election problem (GEP)
Given an (un)oriented ring R with input configuration S, if possible elect a vertex, else elect an edge.

In the course of our investigation on the Boolean case, we shall also consider the problem of computing well-known Boolean functions such as AND and XOR.

Given a problem P we shall denote by $P(S)$ the instance of P when the input string is S. Given two problems P and Q, we denote by $P \geq Q$ the fact that any solution to P implies a solution to Q, and by $P \equiv Q$ the fact that both $P \geq Q$ and $Q \geq P$.

In the following, when considering the message complexity, we will omit to say that messages are bounded and contain at most $O(\log n)$ bits.

3. General Properties

In this section we first establish some general properties on resolvability of the election and sorting problem, as well as on their relationship. In particular we show that the nature of this relationship depends directly on the value of $\delta(S)$.

3.1. Basic Results

A basic negative well known result is the following and follows from [3]:

Lemma 1 *No non-constant function can be computed in asynchronous rings if n is not known.*

From this we have:

Corollary 1 *The GEP and MSP are deterministically unsolvable if n is not known.*

Hence in the following we will always *assume* that n *is known*.

We now establish a necessary and sufficient condition for resolvability of GEP.

Theorem 1 *Let n be known and let S be a string given as input to an anonymous ring. $GEP(S)$ is solvable iff S is aperiodic.*

We now recall the following obvious result:

Lemma 2 $(VE \geq EE)$.

Another simple property is the following:

Theorem 2 $VE(S) \geq MSP(S)$.

3.2. Characterization: The Case $\delta(S) \neq 2$

Consider first the case $\delta(S) = 1$. In this case

Theorem 3 *If $\delta(S) = 1$ then GEP is unsolvable, MSP is already solved.*

It is interesting to observe that to recognize whether $\delta(S) = 1$ is a non-trivial problem. The problem P_u of determining whether $S = u^n$ (where $u \in Z_v = \{0, \ldots, v-1\}$) is in fact equivalent to the problem of computing the AND of a Boolean string.

Theorem 4 $AND \equiv P_u$.

PROOF Let us first show that $P_u \geq AND$. Let us assume we have solved P_u. If S is a Boolean string, then $Z_v = \{0,1\}$, and trivially $P_1(S) = AND(S)$ since if $P_1(S) = 1$ then $S = 1^n$ and therefore $AND(S) = AND(1^n) = 1$, otherwise $P_1(S) = 0$, i.e., $S \neq 1^n$ and $AND(S) = 0$. Let us now show that $AND \geq P_u$. We move from a configuration $S = s_1 \ldots s_n$ to $S' = s'_1 \ldots s'_n$ where if r_i has $s_i = u$ then $s'_i = 1$ else $s'_i = 0$. Trivially $AND(S') = P_u$ since $AND(S') = 1$ iff $S = u^n$. ■

Another simple case is $\delta(S) > 2$.

Theorem 5 *If $\delta(S) > 2$ then $MSP(S) \equiv VE(S)$.*

3.3. Characterization: The Case $\delta(S) = 2$

The only case left is when $\delta(S) = 2$. Unlike the others, this case is rather complex; we will be using a sequence of technical lemmas. In the following, w.l.o.g., we will assume that the two values in the sequence are 0 and 1, and will omit to state that $\delta(S) = 2$.

Lemma 3 $(EE \geq MSP)$.

PROOF Assume an edge has been elected. Let e be the elected edge, and let x and y be the incident vertices. In the oriented case, one of the two vertices, say x, 1) becomes the leader, 2) computes $d_u(S)$ (e.g., by sending a counter around the ring), and 3) tells the first $d_0(S)$ vertices to assume value 0 and the rest to assume value 1. In absence of orientation, $d_u(S)$ is computed (redundantly) in both directions; two cases arise depending on whether $d_0(S)$ is even

or odd. If $d_0(S)$ is even, the first $d_0(S)/2$ vertices on both sides of e (including x and y) become 0, all others become 1. Consider now the case when $d_0(S)$ is odd. If n is even, the strings starting from x and y and ending with edge e are distinct, hence a leader can be uniquely chosen. If n is odd, a leader is uniquely determined (e.g., the only vertex at distance $(n-1)/2$ from both x and y). In all these cases the chosen leader executes steps 2) and 3) of the oriented case. ■

Theorem 6 *In oriented rings,* $VE \equiv MSP$.

In the case of unoriented rings, the relationship between these problems is slightly more complicated.

Lemma 4 *In unoriented rings*

- *If* $d_0(S)$ *is odd,* $MSP(S) \geq VE(S)$*;*
- *if* n *is odd* $MSP \geq VE$*;*
- *if both* n *and* $d_0(S)$ *are even, then* $MSP(S) \geq EE(S)$.

PROOF Assume a string S is sorted; i.e., $S = s_1 \ldots s_n = 0^{d_0(S)}1^{d_1(S)}$.

1) If $d_0(S)$ is odd, the vertex $r_{\lceil (d_0(S)/2) \rceil}$ is uniquely determined and can be elected as a leader.

2) if n is odd either $d_0(S)$ or $d_1(S)$ is odd. The first case is already dealt with; in the second case, the vertex $r_{d_0(S)+\lceil d_1(S)/2 \rceil}$ is uniquely determined and can become leader.

3) A unique edge can be determined and thus elected, e.g., the edge incident on vertices $r_{(d_0(S)/2)}$ and $r_{(d_0(S)/2+1)}$. ■

Theorem 7 *In unoriented rings* $MSP \equiv EE$.

On the other hand,

Theorem 8 *In unoriented rings* $VE(S) \equiv MSP(S)$ *iff* n *or* $d_0(S)$ *is odd.*

By definition of GEP, from theorem 7 and theorem 8, it follows that:

Theorem 9 $MSP \equiv GEP$.

Let us now show how certain values of n can help finding a solution to the GEP and MSP.

Theorem 10 MSP *and* VE *are deterministically solvable if* n *is prime.*

Finally we establish a basic relationship between MSP and the problem of computing the XOR of a string S with $\delta(S) = 2$.

Theorem 11 $MSP \geq XOR$.

4. Sorting and electing a leader in anonymous asynchronous rings

In this section, we show how to use the results related to the properties of the string S and to the value n, in order to solve the GEP and MSP in anonymous asynchronous rings. We consider all boolean strings (i.e., $\delta(S) \leq 2$).

4.1. Oriented rings

In this section, we first present an algorithm that solves the GEP and MSP for the case n prime. As shown later the algorithm is optimal. For the case n not prime, we give another algorithm that will be shown later to lead to a good average case on every input and every value of n.

All the algorithms presented consider $R(S)$ and solve $GEP(S)$ or $MSP(S)$, if a solution exists; in the case no solution exists, all vertices become aware of this fact.

4.1.1. Case n prime. Let us first present an algorithm that is used for the case n prime. It is divided into three steps. In the first one every processor starts in an *active-step 1* state and has an input bit b; different cases may arise: a) it receives a total of $n-1$ bits equal to b and in this case moves to an *all-equal* state since it detects that $S \in \{0^n, 1^n\}$ and therefore the algorithm can end (no leader can be elected and S is already sorted); b) it sends and receives bits until it receives a bit $\neq b$; it chooses as a value the number of b's it has collected plus its own, sends its value to the left and to the right and then moves to an *active-step 2.1* state; c) it receives messages from other processors that are in the next state (active-step 2.1) and in this case it becomes *passive*.

Step 2 is divided into two sub steps: active-step 2.1 and active-step 2.2. In active-step 2.1 state, a processor receives the values of its active neighbours. If its value is a local maxima, it remains active, otherwise it becomes passive. Every active processor p sends a counter to the right and moves to an *active-step 2.2* state. Passive processors that receive this counter increase it and forward it. In active step 2.2 state p eventually receives a counter from the left; if this value is n, p knows that this is its own message and that all the other processors are passive, it becomes *leader* and moves to an *active-step 3* state, otherwise it chooses the value of the counter as its new value and moves back to active-step 2.1. Every passive processor forwards messages and, when appropriate, it increases counters.

Finally, at active-step 3 different actions are taken depending on whether the problem to be solved is the election or sorting. In case of election, the leader sends its value around which transforms all other processors from passive to *defeated* and enters a final state *elected*. In case of sorting, it determines (by circulating a counter) $d_0(S)$, chooses value 0 and it tells the first $d_0(S) - 1$ processors on its right

to change their bit into 0 and the others into 1; once a processor knows its final value it becomes *sorted*.

We now introduce an important definition. Any string S can be viewed as a sequence of pairs of alternating blocks of 0's and 1's whose lengths are denoted by z_j and t_j, respectively, let $l(S)$ denote the number of such pairs. Let $z_{max} = \max\{z_j\}$, $t_{max} = \max\{t_j\}$, for $j = 1, 2, \ldots, l(S)$. When no ambiguity arises we will omit the subscripts and use l instead of $l(S)$.

Theorem 12 *The above algorithm correctly solves the GEP and MSP for the case n prime (and MSP also for $S \in \{0^n, 1^n\}$). The algorithm requires the exchange of at most $O(\sum_{j=1}^{l}({z_j}^2 + {t_j}^2) + n \log n)$ messages.*

In a later section we will show that this algorithm is optimal.

4.1.2. Case n not prime. Let us now consider the case when n is not prime. If we apply a trivial input collection algorithm we can solve the problem in $O(n^2)$ messages. In fact, if the string is periodic, every processor will detect it; if it is not periodic, a unique maximal lexicographical shift of the string exists (see property 2) and the processor that collects it will be elected as leader and will do the sorting, if needed.

We now present a good average case (with respect to the input) algorithm. We will use the notation of Kolmogorov random [9]; briefly, an n bit string is Kolmogorov random (k-random for short) if the length of the shortest program outputting the string is longer than $n - \log n$ bits. In this context it is trivial to see that the fraction of Boolean strings of length n that are not k-random is only $1/n$ ($2^{n-\log n}/2^n = 1/n$). For further details refer to [9].

The algorithm that we now present is based on a fact that is derived from some results in [8, 14]:

Property 4 *[8, 14] There exists a constant C such that, all substrings of length $C \log n$ of any n-bit cyclic k-random string are different.*

From this fact it trivially follows:

Property 5 *There exists a constant C' such that, all substrings of length $C' \log n$ of any n-bit cyclic k-random string and of its reverse string are different.*

The main idea of the algorithm is that every processor starts in an *active-step 1* state where it collects at least $C \log n$, but no more than $n-1$ values, continuing as long as receiving values equal to b. If the number of collected values is $n-1$, it moves to an *all-equal* state and it ends, since it detects that $S \in \{0^n, 1^n\}$ and therefore it knows that no leader can be elected and that the string is already sorted. If exactly $C \log n$ values have been collected it uses the received string as a value and moves to an *active-step 2* state; otherwise, it chooses as a value the number of received bits and moves to active-step 2 state. If a processor in active-step 1 state receives an active-step 2 message it becomes passive. All active processors that move to active-step 2 state run a Hirschberg and Sinclair leader election algorithm [7] using the chosen values as identifiers. Since those values might not be distinguished, more than one processor can become leader. The Hirschberg and Sinclair algorithm can be easily modified to handle this case (e.g., by neither stopping, nor "killing" encountered processors with the same value, and continuing for exactly $\lceil \log n \rceil$ steps). Every leader then moves to an *active-step 3* state and sends a counter around to determine if it is unique; in this case it becomes *elected* and eventually sorts. Otherwise, every leader sends a stop bit around and all processors (even the passive one) move to an *active-step 4* state. In this state, every processor runs an input collection. If S is aperiodic, the processor that has collected the unique maximal lexicographical rotation of the string is elected and eventually sorts; if S is periodic, all processor move to an all-equal state and end.

Theorem 13 *The above algorithm correctly solves the GEP and MSP for the case S aperiodic (and MSP also for $S \in \{0^n, 1^n\}$); it requires on average, with respect to all possible input strings, $O(n \log n)$ messages.*

4.2. Unoriented rings

In this section we show how to modify the given algorithms for oriented asynchronous rings to solve the GEP and MSP for unoriented rings.

4.2.1. Case n prime. Let us first consider the case of n prime. The main idea is that every processor can run separate executions of algorithm of section 4.1.1. in both directions, and as a result, two leaders are elected if $S \notin \{0^n, 1^n\}$, or it is detected that $S \in \{0^n, 1^n\}$. If $\delta(S) = 2$, the two leaders (by each sending counters) compute the two distances c and c' (n is known). Since one of them is even and the other odd, they send an election message to the processor in the middle of the path of the even distance; this processor moves to an *elected* state and can eventually sort. As usual, passive processor forward (and, if appropriate, increase) the received values.

Observe that, since the algorithm of section 4.1.1. is executed concurrently a processor can be in different states with respect to each execution. Notice that it is possible that a passive processor becomes elected (because it is in the middle of the path).

Theorem 14 *The above algorithm correctly solves the GEP and MSP for the case n prime and S aperiodic (and*

MSP also for $S \in \{0^n, 1^n\}$) in an anonymous unoriented ring and it requires $O(\sum_{j=1}^{l}({z_j}^2 + {t_j}^2) + n \log n)$ messages.

4.2.2. Case n not prime. Let us now consider the case n not prime.

We now give a good average case (with respect to the input) algorithm. The main idea is that every processor runs the algorithm of section 4.1.2. simultaneously and separately in both directions. If $S \in \{0^n, 1^n\}$ or S is periodic, the algorithm will stop detecting such cases, otherwise it elects two leaders v and y which move to a new state. In this state if $v > y$ (or $y > v$) then v (y) is elected, otherwise the right and left distances c and c', between v and y are computed; if $c \neq c'$ and either c or c' is odd the processor in the middle of the smallest odd distance is elected. If both c and c' are even or equal run an input collection algorithm. Once the strings have been collected, the two leaders can determine whether there exists a vertex which is unambiguously determinable in S and $\bar{S}$; if so, such a vertex becomes the only elected vertex. Otherwise, VE is not solvable but an edge can be uniquely determined in S and $\bar{S}$ since the string is aperiodic.

Theorem 15 *The above algorithm correctly solves the GEP and MSP for S aperiodic (and MSP also for $S \in \{0^n, 1^n\}$), and requires on the average, with respect to all possible input strings, the exchange of at most $O(n \log n)$ messages.*

5. Lower bounds

In this section we study the lower bounds for the asynchronous (un)oriented rings.

We first have to define the following family:

Definition 1 *Given a string S consisting of alternating strings of 0's and 1's, z_i and t_i, we call $F(S)$ the family of all the boolean functions $f : S \to \{0,1\}$, $f \in F(S)$, such that $\forall i \leq z_{max}$, $\forall j \leq t_{max}$, $\exists c_1, c_2 \ \{0,1\}^{n-i}$, $\exists c_1', c_2' \in \{0,1\}^{n-j}$, such that: $f(0^i c_1) = f(0^n)$, and $f(0^i c_2) \neq f(0^n)$; $f(1^j c_1') = f(1^n)$, and $f(1^j c_2') \neq f(1^n)$.*

Lemma 5 *Given a string S, the computation of every boolean function $f \in F(S)$ in an anonymous (un)oriented ring, requires at least $\Omega(\sum_{j=1}^{l}({z_j}^2 + {t_j}^2))$ messages.*

Theorem 16 *Given a string S the GEP and MSP on S require at least $\Omega(\sum_{j=1}^{l}({z_j}^2 + {t_j}^2) + n \log n)$ messages in an asynchronous ring.*

Corollary 2 *By theorem 12, theorem 14, theorem 16, algorithm of section 4.1.1. and algorithm of section 4.2.1. are optimal.*

We finally prove the following:

Lemma 6 *For almost all input strings S, $\sum_{j=1}^{l}({z_j}^2 + {t_j}^2) \in O(n \log n)$.*

Corollary 3 *For almost all input strings the lower bound of theorem 16 reduces to $\Omega(n \log n)$ messages.*

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